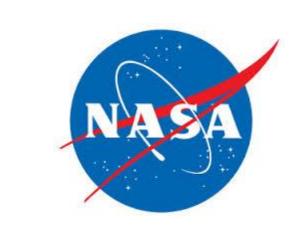
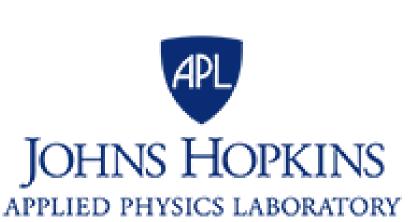


# Ku-Band Traveling Wave Slot Array Using Simple Scanning Control

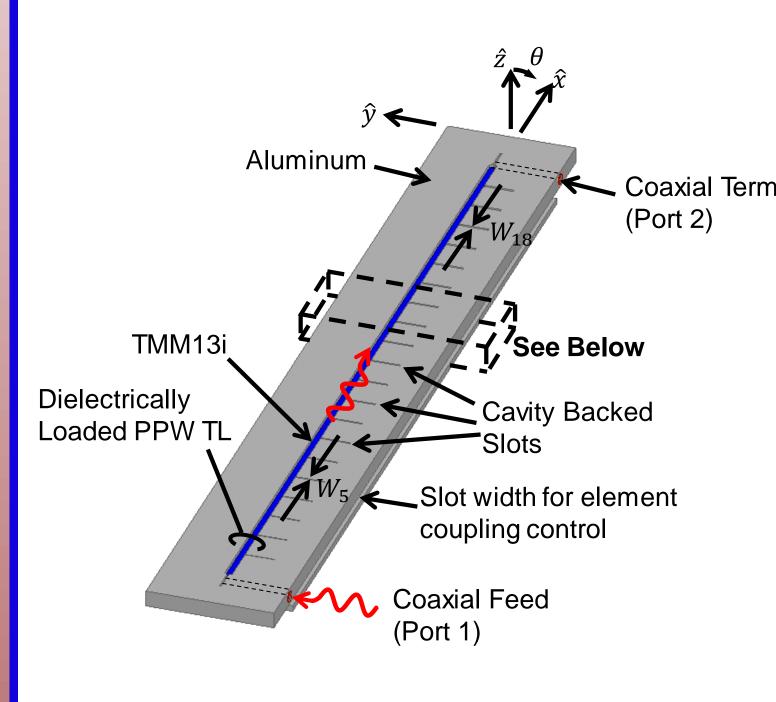




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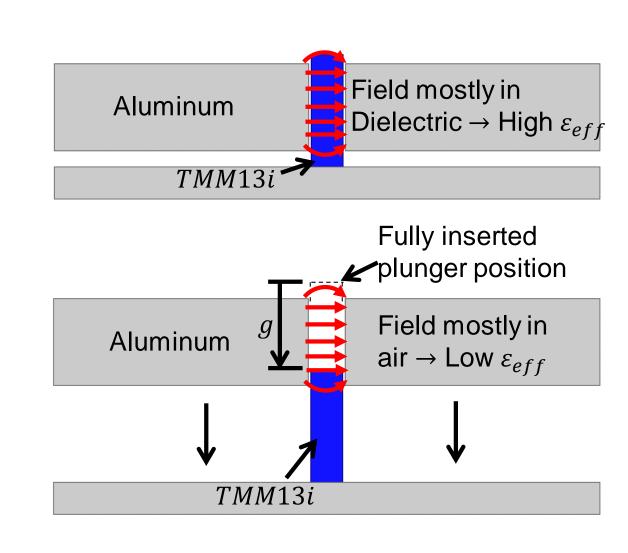
Abstract: This poster introduces a feeding concept aimed at simplifying the backend (phase shifters) of traditional phased arrays. As an alternative to traditional phased arrays, we employ a traveling wave array (TWA) using a single feedline whose propagation constant is controlled via a single, small mechanical movement without a need for phase shifters to enable scanning. Specifically, a dielectric plunger is positioned within a parallel plate waveguide (PPW) transmission line (TL) that feeds the TWA. By adjusting the position of the dielectric plunger within the PPW feeding the TWA, beam steering is achieved. A 20 element array is designed at 13GHz shown to give stable realized gain across the angular range of  $-25^{\circ} \le \theta \le 25^{\circ}$ . A proof of concept array is fabricated and measured to demonstrate and validate the concept's operation.

## **Operation Principle**

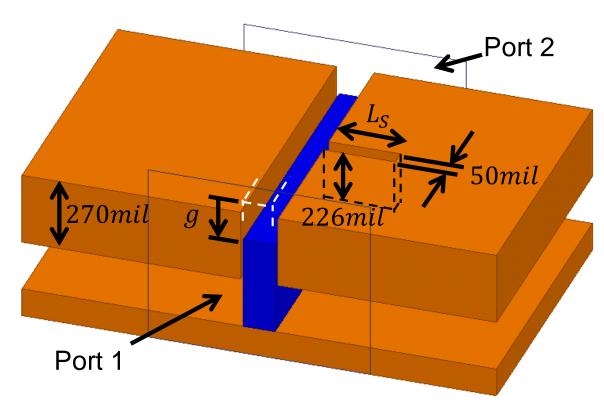


Maximum extent

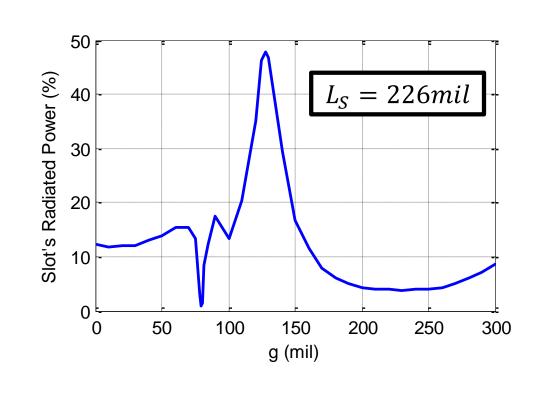
- Array elements fed via propagation reconfigurable transmission line
- $k_{eff}$  reconfigured via small mechanical movement
- Phase delivered to each element a function of  $k_{eff}$
- Array scanned with only the small mechanical movement

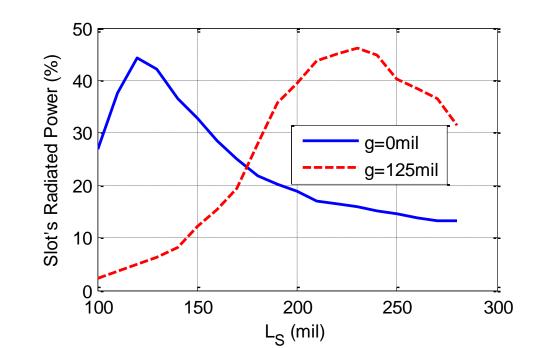


## Rectangular Cavity Backed Slot

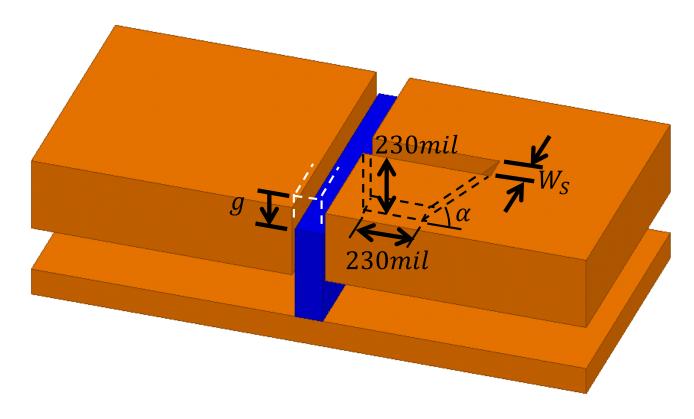


- Cavity backed slot becomes detuned as the plunger is adjusted
- Resonant length of the cavity backed slot varies with plunger position

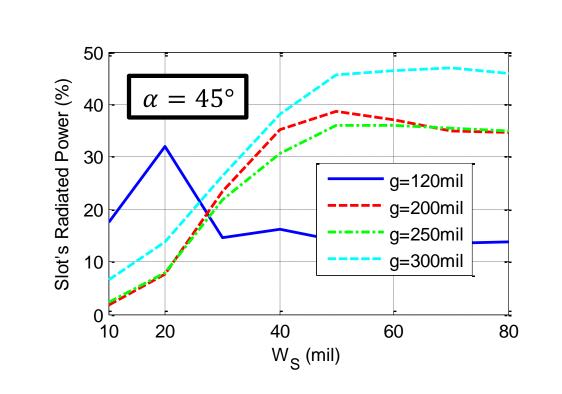




### Non-Rectangular Cavity Backed Slot



- By angling the back of the cavity we lower the Q value •  $W_S$  is used to control the
- coupling to each element
- A large range of coupling achievable is desired



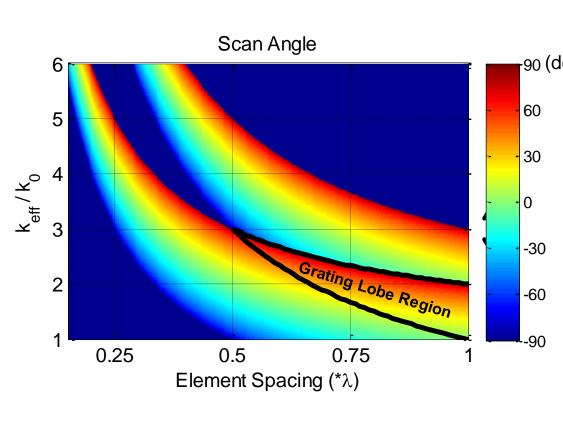
Iteratively Readjust Slot

Widths, Wi, to Account for

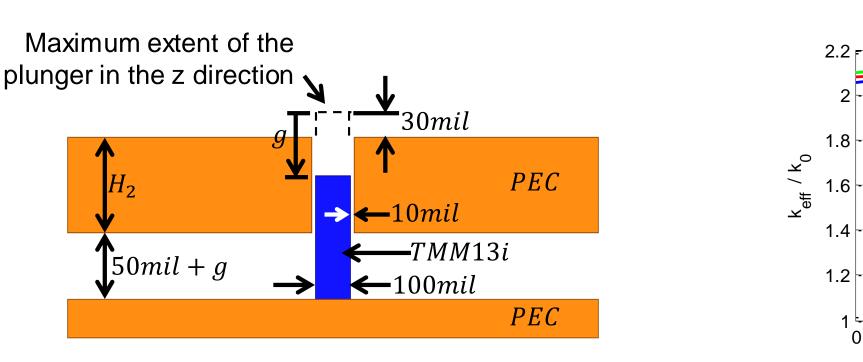
Inter-Element Coupling

(Targeting  $B_i = A_i$ )

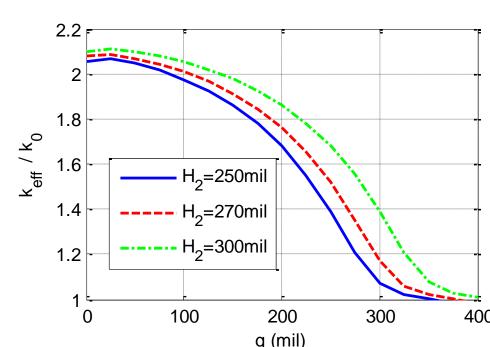
### Transmission Line Design



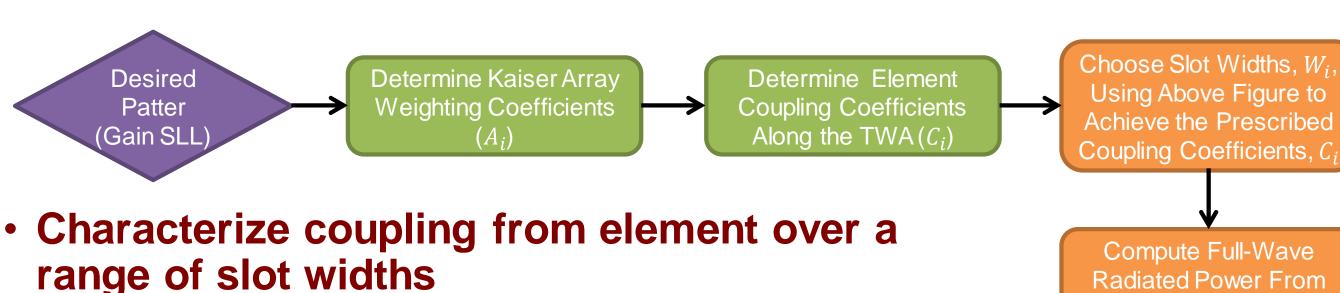
- Scan range a function of element spacing and TL  $k_{eff}$
- $-30^{\circ} \le \theta \le 30^{\circ}$  scanning is achieved with  $1.04 \leq \frac{k_{eff}}{l} \leq 2.04$ for and element spacing of  $0.65\lambda$
- Line achieves the necessary  $k_{eff}$



agility at  $H_2 = 270mil$ 

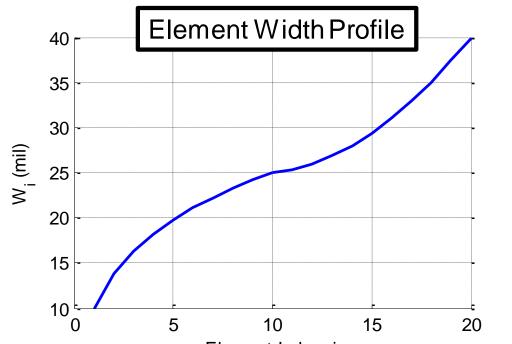


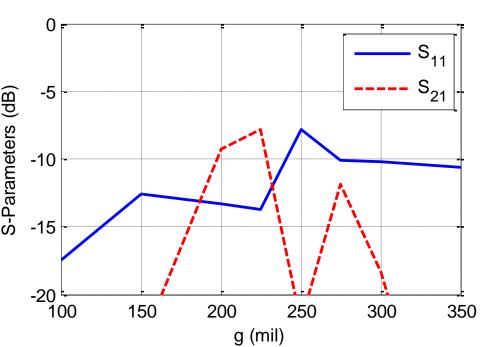
### **Array Design Procedure**



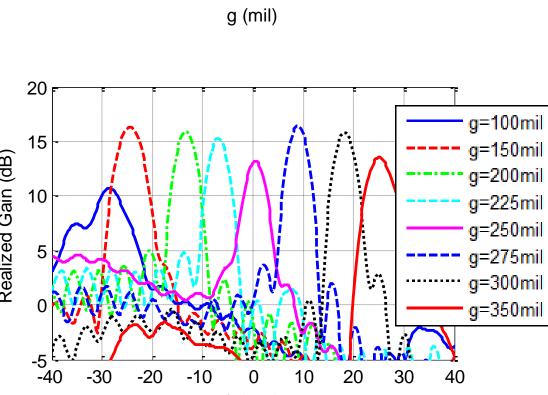
- Choose the element widths along the TWA to achieve the desired Kaiser taper
- Iteratively adjust slot widths to account for element reflections and mutual coupling until desired pattern is achieved

# Initial Design Performance

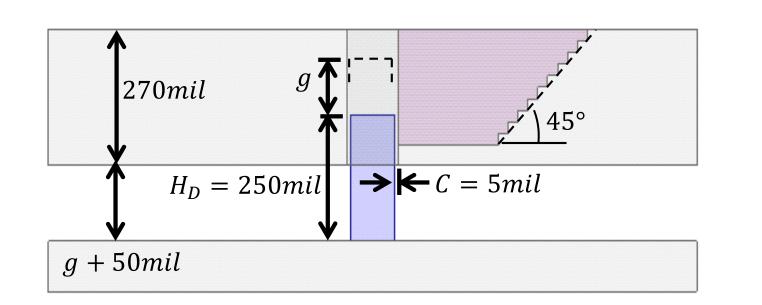


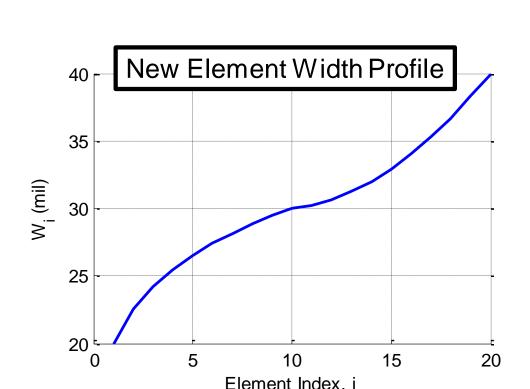


- S-Parameters generally less than -10dB except around boresight scan as expected
- Scanning of  $-25^{\circ} \le \theta \le 25^{\circ}$
- Consistent realized gain level across scan range



### Increased Manufacturability



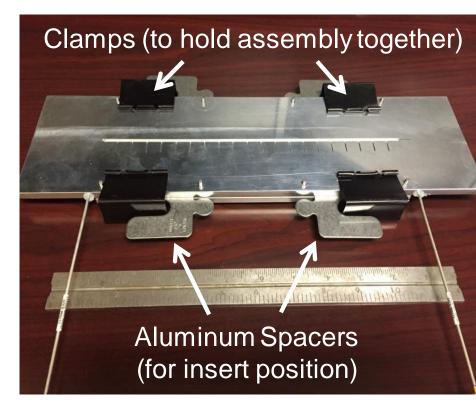


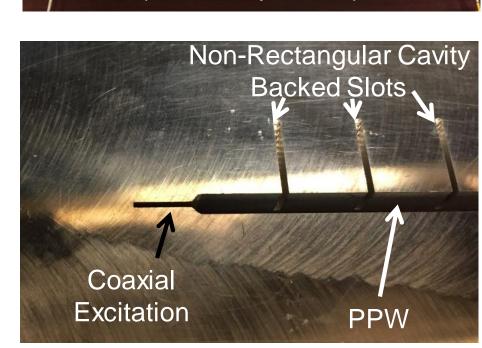
### Reduce fabrication complexity

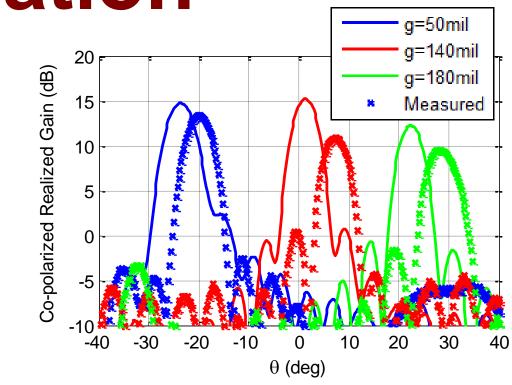
- 10 Steps to approximate cavity back
- Reduced plunger height
- Alter TL geometry and element spacing to achieve desired scan range



### **Prototype Validation**







- Measurements generally agree with simulation
- Realized gain is down compared to simulated due to differences in TL geometry
- Measured scan angle is more positive, also due to differences in TL geometry